

# **JBT-CTRL-556**

**Docking station drive integrated controller**

**Hardware ManualV1.0.0**

## Table of contents

1. Product Introduction.....	1
1.1Product Overview.....	1
1.2Product functions and features.....	1
1.3Application areas.....	1
2. Electrical, Mechanical and Environmental Specifications.....	1
2.1Mechanical Installation Drawing.....	1
2.2Electrical Specifications.....	2
3. Driver interface and wiring introduction.....	2
3.1Interface Diagram.....	2
3.2Interface Description.....	3
3.2.1Power interface.....	3
3.2.2Motor Interface.....	3
3.2.3Signal Input Interface.....	3
3.2.4Timeout setting potentiometerSRO,SRI.....	3
3.2.5Signal output interface.....	4
3.2.6External key input signal interface.....	4
3.2.7DIP switch settings.....	5
3.3Interface circuit description.....	6
3.3.1Input Interface Circuit.....	6
3.3.2Output interface circuit.....	6
3.3.3Photoelectric sensor input interface circuit.....	7
3.3.4Analog Input Interface Circuit.....	7
3.3.5Motor output interface circuit.....	7
3.3.6External switch input.....	8
IV. Indicator lights and alarm indicators.....	9
4.1Power supply, alarm indicator light.....	9
V. Version Revision History.....	10

## 1. Product Introduction

### 1.1 Product Overview

JBT-CTRL-556The docking station drive and control integrated controller is a special control panel launched for the "docking station" industry.2Road external Potentiometer speed regulation function, speed range0~250rpm, synchronous control can be achieved2road42or57series of motors, combined with2Road or3Road Sensor signals, input and output signals of upper and lower stations, key control signals, can realize standard mode,NGMode, marking mode, cylinder Mode Four control modes. This product has rich functions, superior performance, simple use, and can be widely used in the docking station equipment industry.

### 1.2 Product functions and features

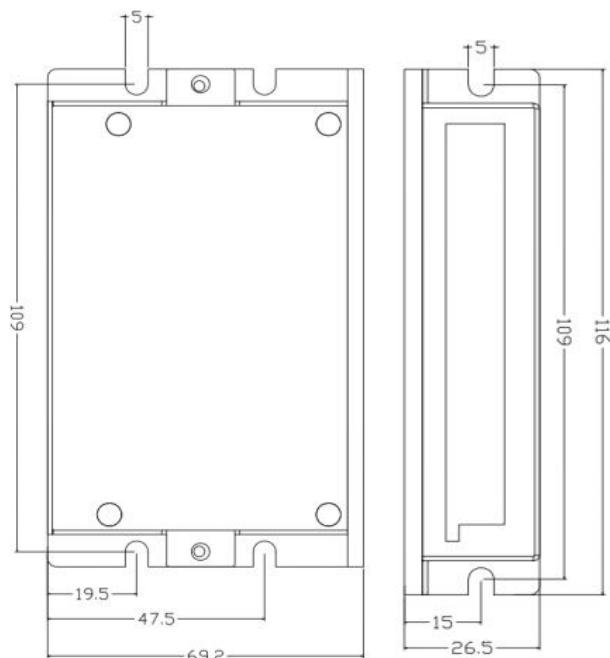
- **Rated operating voltage:**DC24V;
- **Matching motor:**GR42HB40,GR42HB48,GR42HB60,GR57HB56,GR57HB76,GR60HB86Series motors;
- **Motor synchronous operation:**Acceptable2Road motor and synchronous operation;
- **Position Sensors:**2Road or3Optional (automatic identification by software), sensorNPNtype;
- **Interface terminals:**Signal,42MotorXH2.54series,57Motor3.81Wiring terminal, power supplyJST-VHseries;

### 1.3 Application Areas

Suitable for docking station equipment.

## 2. Electrical, Mechanical and Environmental Indicators

### 2.1 Mechanical installation drawing



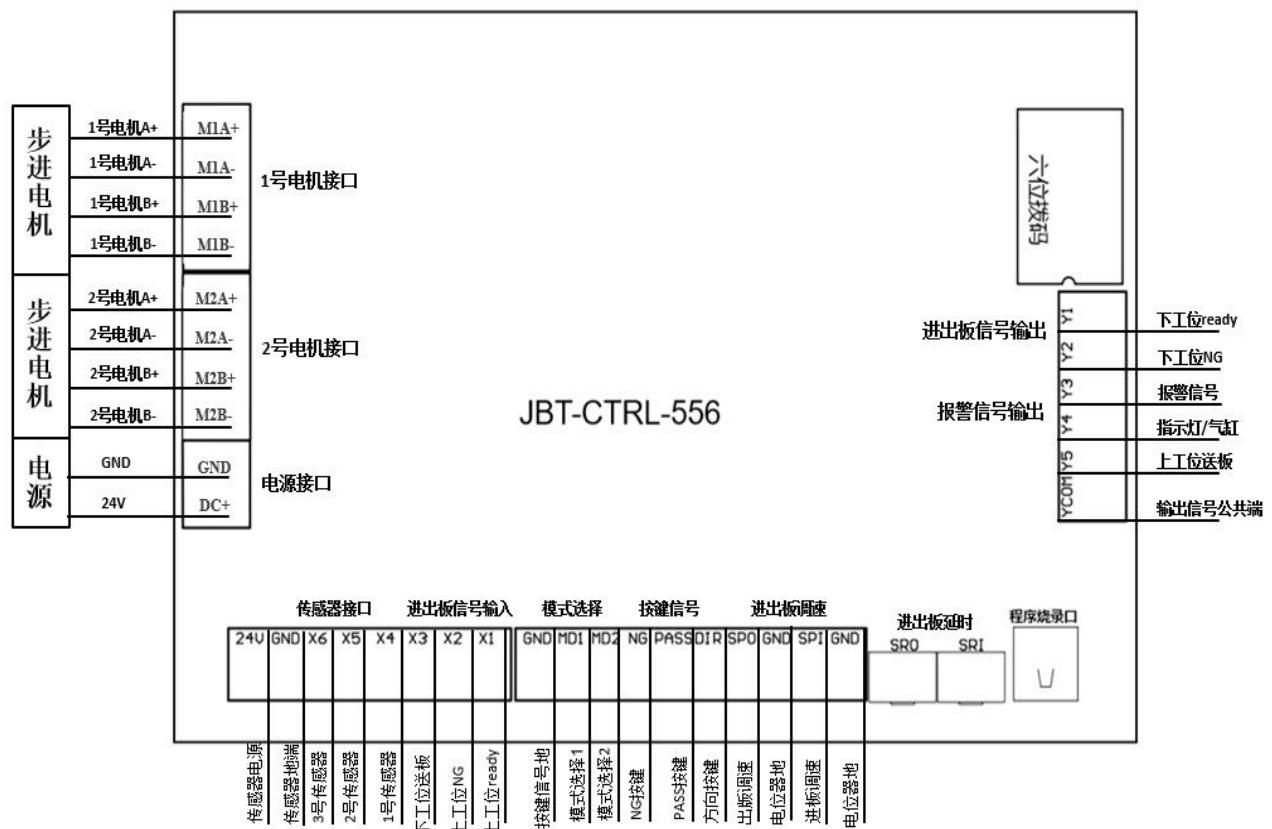
picture2.1Installation Dimensions (Unit:mm)

## 2.2 Electrical Specifications

illustrate	JBT-CTRL-556			
	Minimum	Typical Value	Maximum	unit
Total output current	2.5		4.8	RMS(A)
Input power voltage	12	twenty four	40	VDC
Control signal input current	7	10	16	mA
Running speed	0	-	250	rpm
Insulation resistance	500			MΩ

## 3. Driver interface and wiring introduction

## 3.1 Interface Diagram



picture3.1 JBT-CTRL-556Interface Diagram

### 3.2 Interface Description

#### 3.2.1 Power interface

serial number	name	illustrate
1	DC+	Power input positive terminal, recommended power output voltage is +24V
2	GND	Power input negative terminal

#### 3.2.2 Motor interface

serial number	name	illustrate	name	illustrate
1	M1A+	Same line sequence, 2Motor running direction To the opposite	M2A+	Same line sequence, 1Motor running direction To the opposite
2	M1A-		M2A-	
3	M1B+		M2B+	
4	M1B-		M2B-	

#### 3.2.3 Signal input interface

serial number	name	illustrate
1	X1	and GND connecting means signal input enter
2	X2	
3	X3	
4	X4	catch NPNT Type Photoelectric Sensor
5	X5	
6	X6	
7	24V	Position sensor power positive terminal
8	GND	Position sensor ground

#### 3.2.4 Timeout setting potentiometer SRO, SRI

SRO: Output delay setting potentiometer, range: 0~5s, turn clockwise to increase.

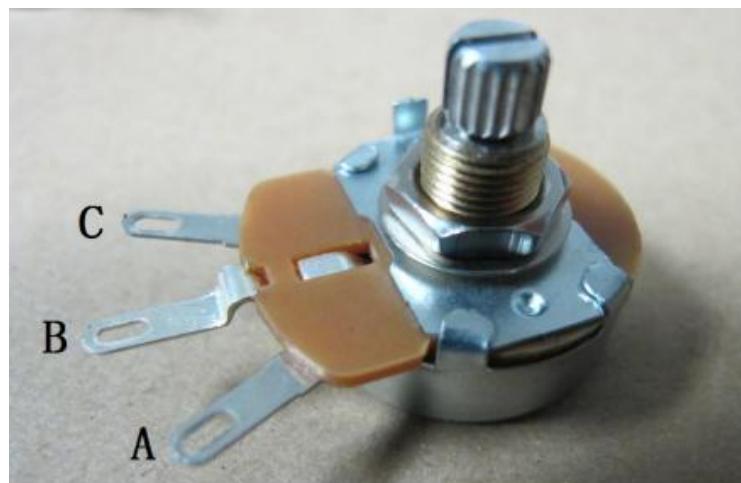
SRI: Board entry timeout setting potentiometer, range: 3~60s, turn clockwise to increase.

### 3.2.5 Signal output interface

serial number	name		illustrate
1	Y1	When the signal is output, the interface YCOMConductivity	readySignal output terminal, this machine sends to the next station machinereadySignal
2	Y2		NGSignal output terminal, this machine sends to the next station machineNGSignal
3	Y3		Alarm output
4	Y4		Indicator light/cylinder control valve output
5	Y5		The board sending signal output terminal sends a signal to the upper station to request the board to be sent.
6	YCOM	Output signal common terminal	

### 3.2.6 External key input signal interface

serial number	name		illustrate
1	GND		Mode switch and key signal ground
2	MO1	andGNDConnection table Indicator signal input	Mode selector switch1Input signal
3	MO2		Mode selector switch2Input signal
4	NG		NGButton end,NGWhen the button is connected, the product is not qualified for connection
5	PASS		PASSButton end,PASSWhen the button is turned on, the product is connected
6	DIR		Running direction button end,DIRWhen the button is turned on, the running direction of the docking station will be changed
7	SPO	PotentiometerA,CCan Interchangeable, can be based on actual Wiring for practical applications	Speed potentiometer on the output boardBend, recommended potentiometer resistance:10K
8	GND		Speed potentiometer on the output boardAorCend
9	SPI		Speed potentiometer connected to the boardBend, recommended potentiometer resistance:10K
10	GND		Speed potentiometer connected to the boardAorCend



### 3.2.7DIP switch settings

<b>SW1</b>	<b>SW2</b>	<b>SW3</b>	<b>Mode Function</b>
off	off	off	Standard Mode
on	off	off	NG Mode 1, 2, 3
off	on	off	Marking mode
on	on	off	NG Mode 1, 4, 5
off	off	on	Cylinder Mode
on	off	on	NG Mode 6
<b>name</b>	<b>Function</b>	<b>illustrate</b>	
SW4	Alarm selection	on: Alarm signal output function is turned on off: Alarm signal output function is closed	
SW5	Current selection	SW5(off),SW6(off):2*1.25A SW5(on),SW6(off):2*1.5A	
SW6		SW5(off),SW6(on):2*2.0A SW5(on),SW6(on):2*2.4A	

Operation mode selection switch and dip switch SW1-SW3The relationship is as follows:

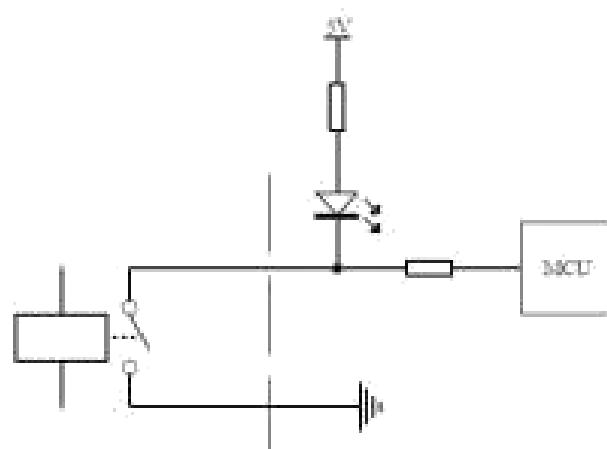
<b>Mode Function</b>	<b>Specific function settings</b>
Standard Mode	Automatic mode 1: Mode selection switch MO1 and MO2 Neither GND On; Automatic mode 2: Mode selection switch MO1 and GND On; Manual mode: Mode selector switch MO2 and GND Connect;
NGMode 1, 2, 3	NGMode 1: Mode selection switch MO1 and GND Connect; NGMode 2: Mode selection switch MO1 and MO2 Neither GND Connect; NG Mode 3: Mode selection switch MO2 and GND Connect;
NGMode 1, 4, 5	NGMode 1: Mode selection switch MO1 and GND Connect; NGMode 4: Mode selection switch MO2 and GND Connect; NGMode 5: Mode selection switch MO1 and MO2 Neither GND Connect;
Marking mode	Marking mode 1: Mode selection switch MO1 and GND On; Marking mode 2: Mode selection switch MO1 and MO2 Neither GND Connect;
Cylinder Mode	Cylinder mode 1: mode selection switch MO2 and GND On; Cylinder mode 2: Mode selection switch MO2 and GND No connection;

### 3.3 Interface Circuit Description

#### 3.3.1 Input interface circuit

As shown2As shown, it is an input switch signal interface circuit, which can receive the switch input signal. The interface circuit is adapted to the following control signals:

- (1) Upper station interface:NGSignal,readySignal;
- (2) Lower station interface:requireSignal;
- (3) Operation mode selection interface: mode selection switchSW1, Mode selector switchSW2;

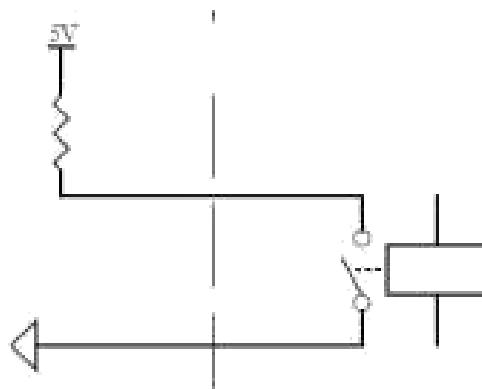


picture2Input switch signal interface circuit

#### 3.3.2 Output interface circuit

As shown3As shown, it is an output switch signal interface circuit, which can output switch signals. This interface circuit is adapted to the following control signals:

- (1) Upper station interface:requireSignal;
- (2) Lower station interface:NGSignal,readySignal;
- (3) Alarm, indicator light/cylinder interface: external alarm, indicator light or cylinder;

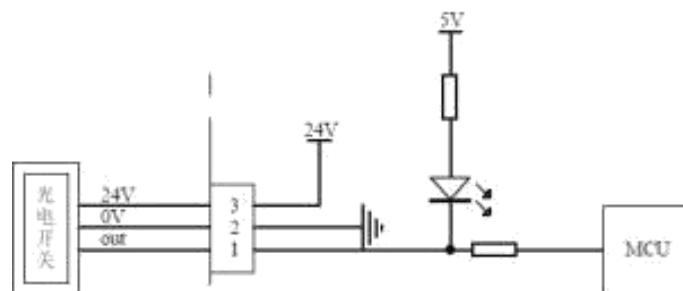


picture3Output switch signal interface circuit

### 3.3.3 Photoelectric sensor input interface circuit

As shown4Shown is a position sensor1-3The input interface circuit is adapted to the following control signals:

- (1) NPNType sensor.

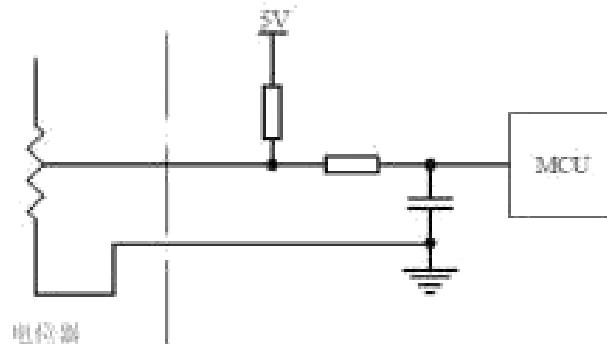


picture4Position sensor input interface circuit

### 3.3.4 Analog input interface circuit

As shown5As shown, it is an analog input interface circuit, which is adapted to the following control signals:

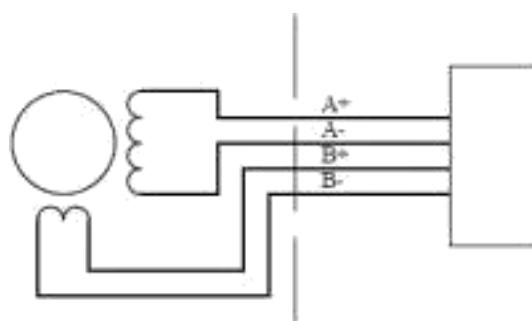
- (1) Input signal of speed regulation into the board;
- (2) Output board speed control input signal;



picture5Analog input interface circuit

### 3.3.5 Motor output interface circuit

As shown6As shown, it is the motor output interface circuit, which is suitable for driving42/57/60series2Phase hybrid stepper motor.

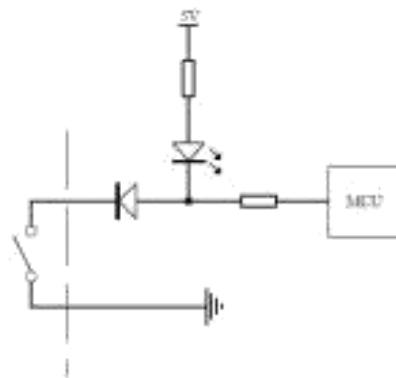


picture6Motor output interface

### 3.3.6 External switch input

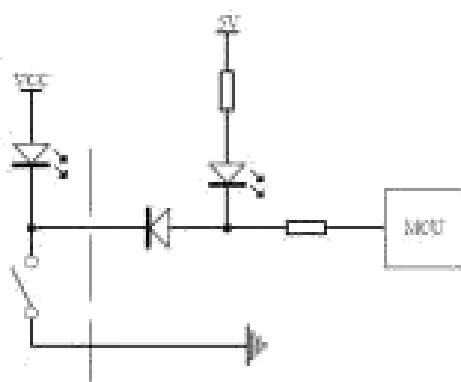
As shown in the following two figures, DIRDirection switch, PASSRe-judgement switch, NGRe-judgment switch input interface circuit.

As shown7As shown, the user adopts ledWiring diagram when pressing a button:



picture7WithoutledButton Wiring Diagram

As shown8As shown, the user adopts ledWiring diagram when pressing a button:



picture8bringledButton Wiring Diagram

#### 4. Indicator lights and alarm indicators

##### 4.1 Power supply, alarm indicator light

ledNumber of flashes		Phenomenon	illustrate
greenled	redled	After the green light flashes, the red light flashes	
0	-	Green light is always on, red light is off	The driver is enabled and the driver board is powered normally

## V. Version Revision History

Version Number	illustrate	Modify deadline	Preparer/Reviewer
V1.0.0	Initial use version;	2024.03.11	HY/TCJ